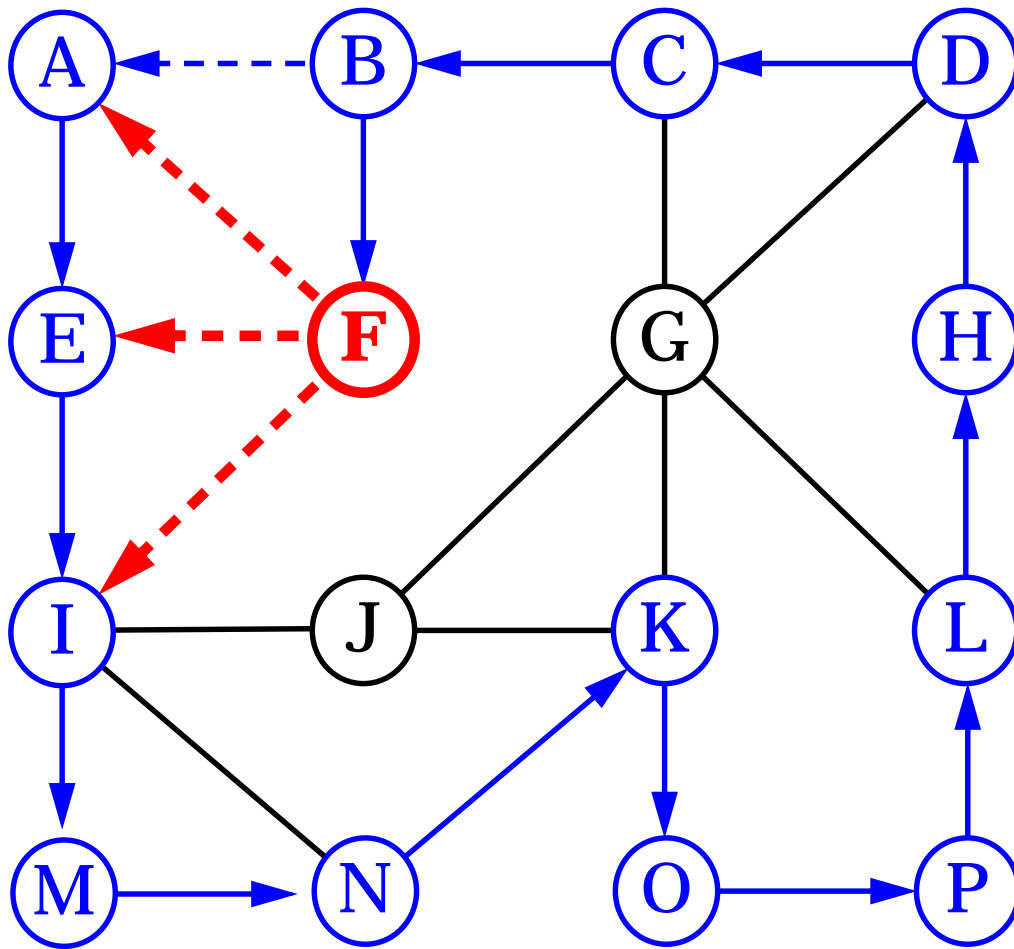


DEPTH-FIRST SEARCH

- Graph Traversals
- Depth-First Search



Exploring a Labyrinth Without Getting Lost

- A **depth-first search (DFS)** in an undirected graph G is like wandering in a labyrinth with a string and a can of red paint without getting lost.
- We start at vertex s , tying the end of our string to the point and painting s “visited”. Next we label s as our current vertex called u .
- Now we travel along an arbitrary edge (u,v) .
- If edge (u,v) leads us to an already visited vertex v we return to u .
- If vertex v is unvisited, we unroll our string and move to v , paint v “visited”, set v as our current vertex, and repeat the previous steps.
- Eventually, we will get to a point where all incident edges on u lead to visited vertices. We then backtrack by unrolling our string to a previously visited vertex v . Then v becomes our current vertex and we repeat the previous steps.

Exploring a Labyrinth Without Getting Lost (cont.)

- Then, if we all incident edges on v lead to visited vertices, we backtrack as we did before. We continue to backtrack along the path we have traveled, finding and exploring unexplored edges, and repeating the procedure.
- When we backtrack to vertex s and there are no more unexplored edges incident on s , we have finished our **DFS** search.

Depth-First Search

Algorithm DFS(v);

Input: A vertex v in a graph

Output: A labeling of the edges as “discovery” edges and “backedges”

for each edge e incident on v **do**

if edge e is unexplored **then**

 let w be the other endpoint of e

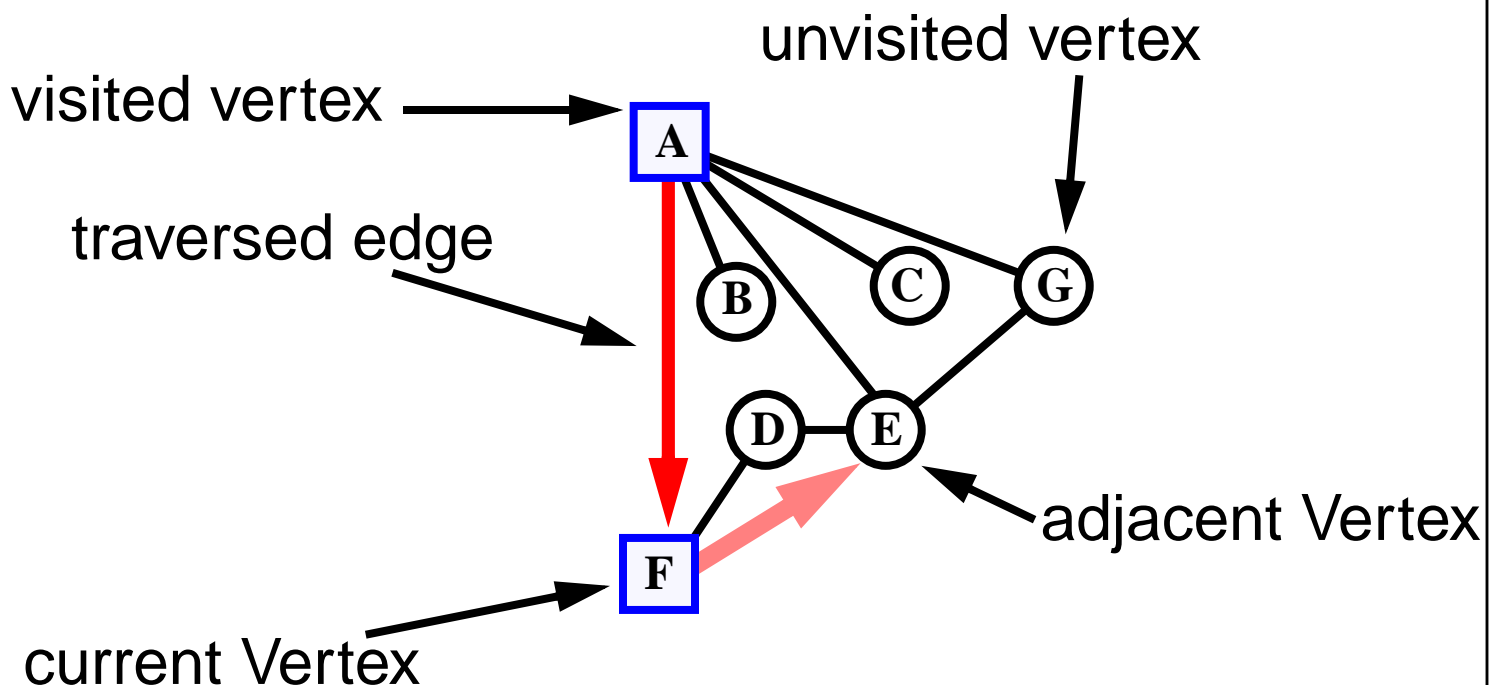
if vertex w is unexplored **then**

 label e as a discovery edge

 recursively call **DFS**(w)

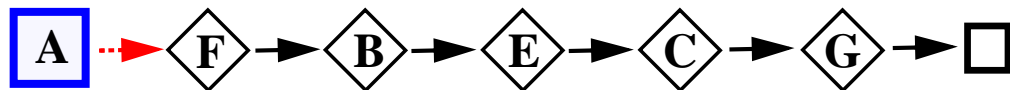
else

 label e as a backedge

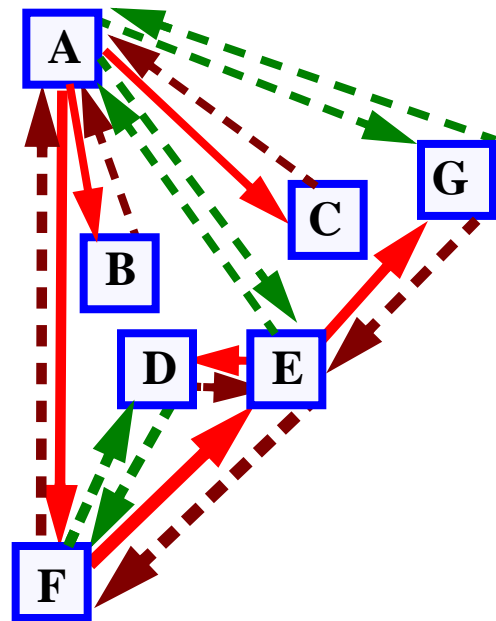
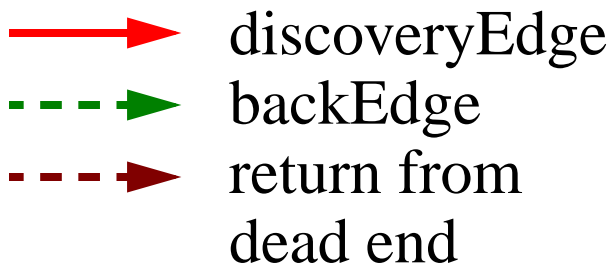


Determining Incident Edges

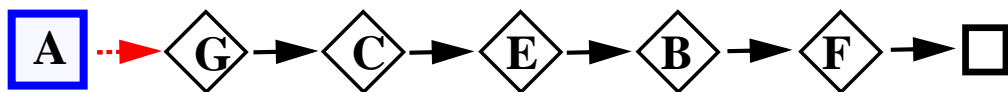
- DFS depends on how you obtain the incident edges.
- If we start at A and we examine the edge to F, then to B, then E, C, and finally G



The resulting graph is:

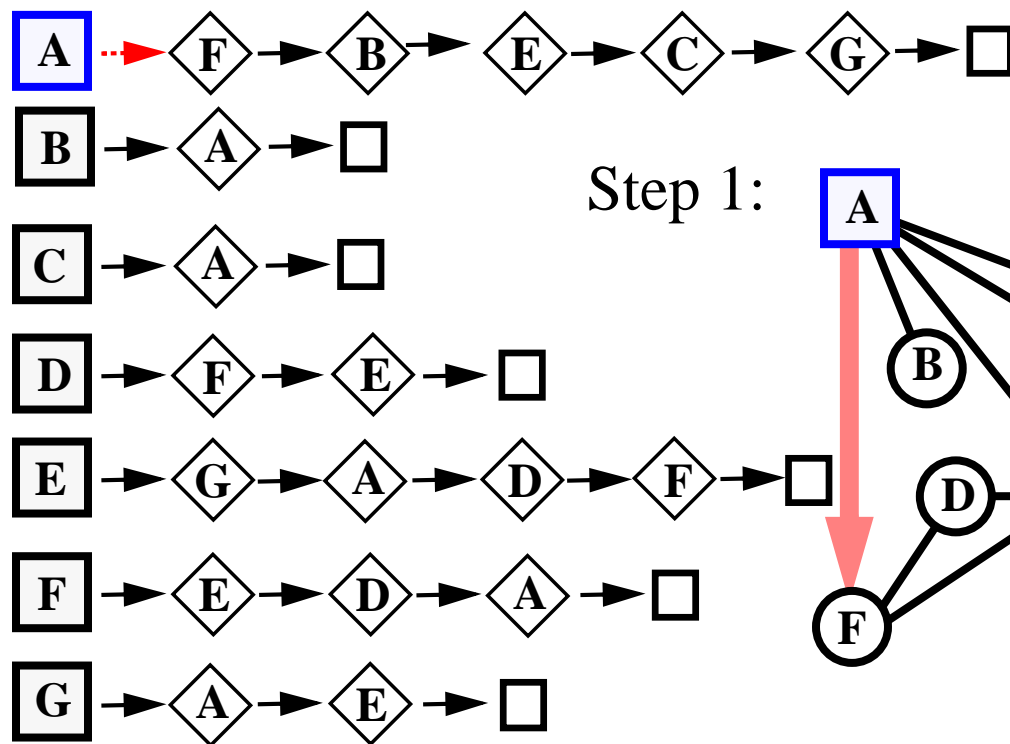


If we instead examine the tree starting at A and looking at F, the C, then E, B, and finally F,

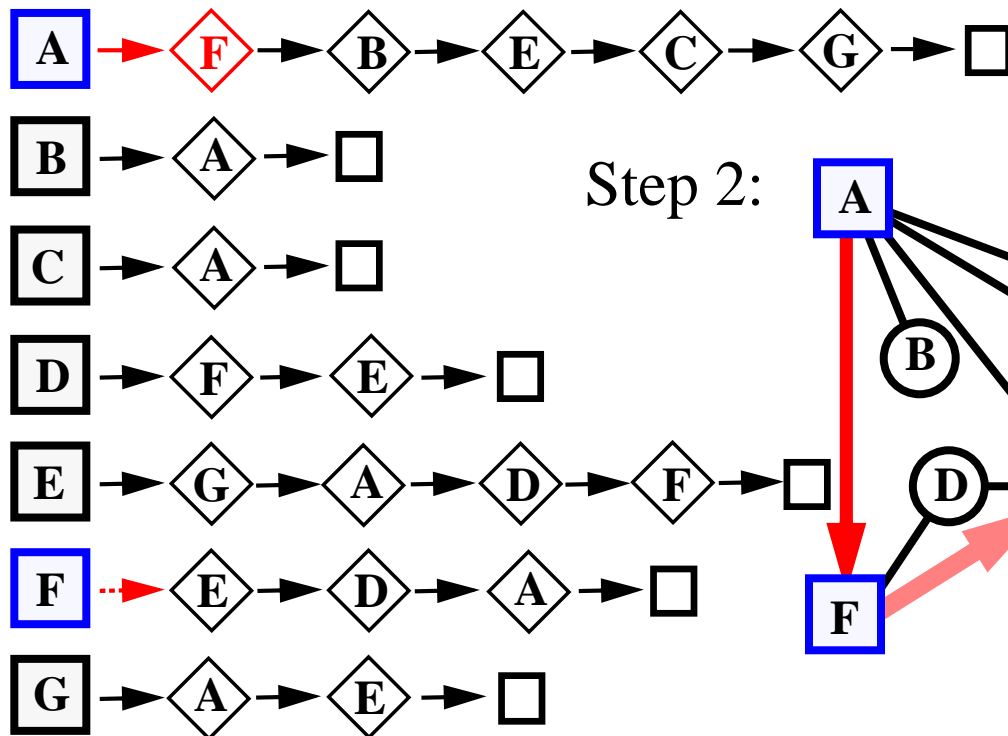
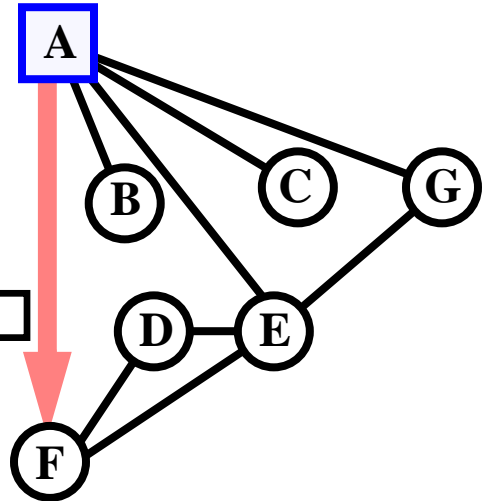


the resulting set of backEdges, discoveryEdges and recursion points is different.

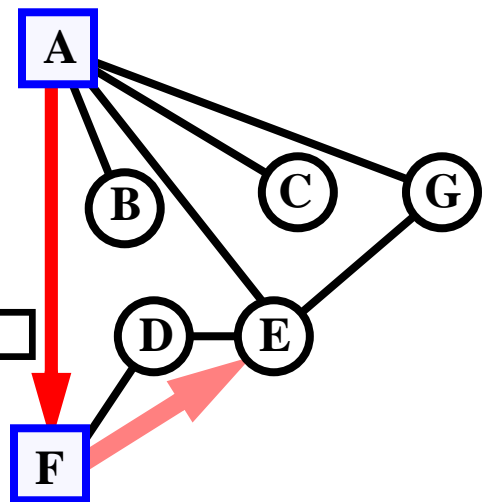
- Now an example of a DFS.

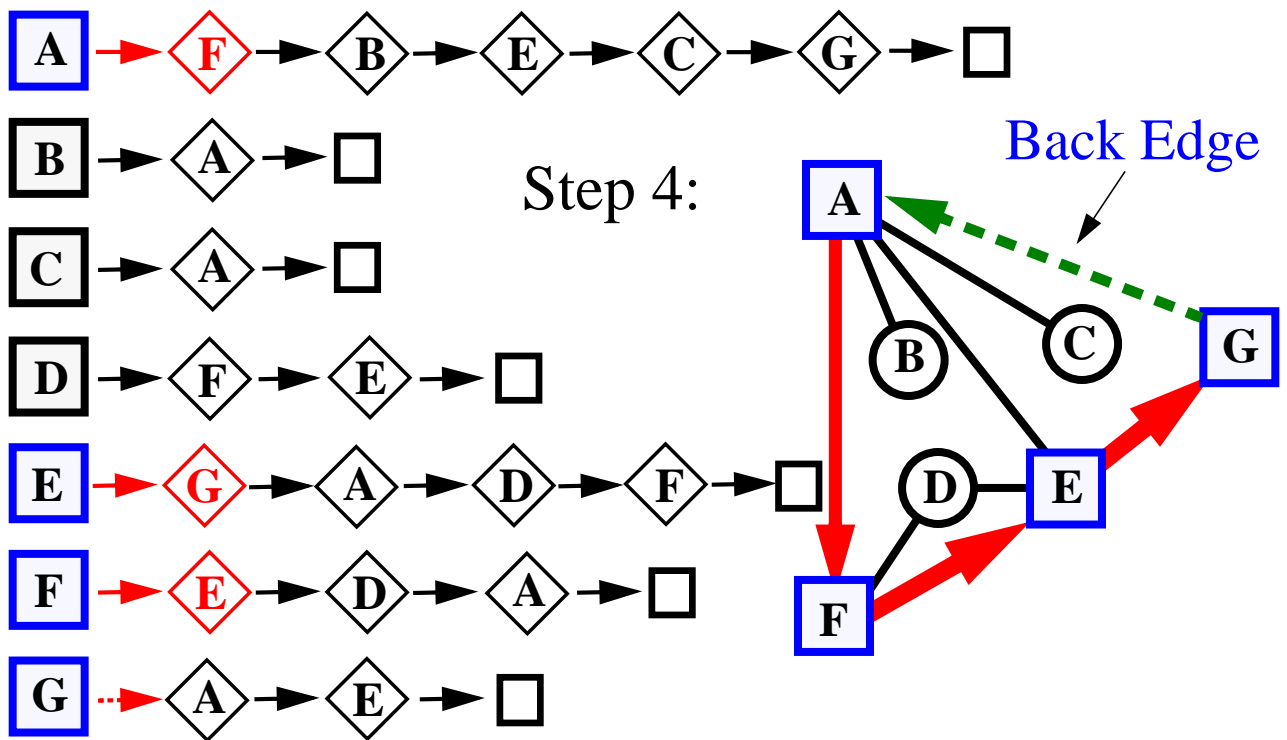
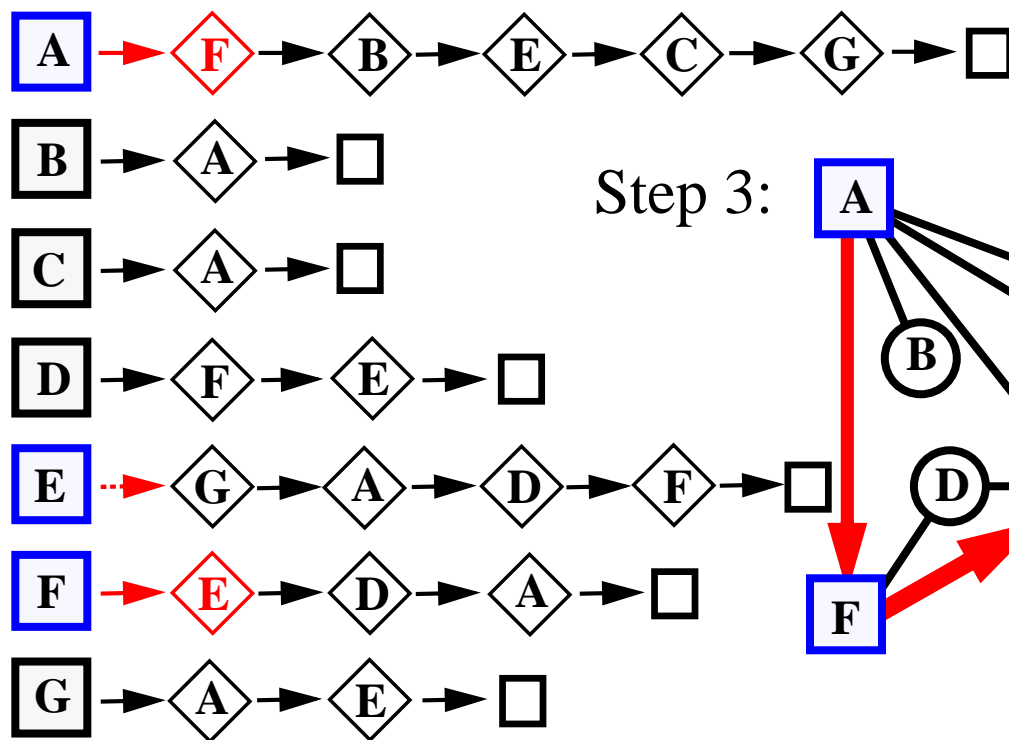


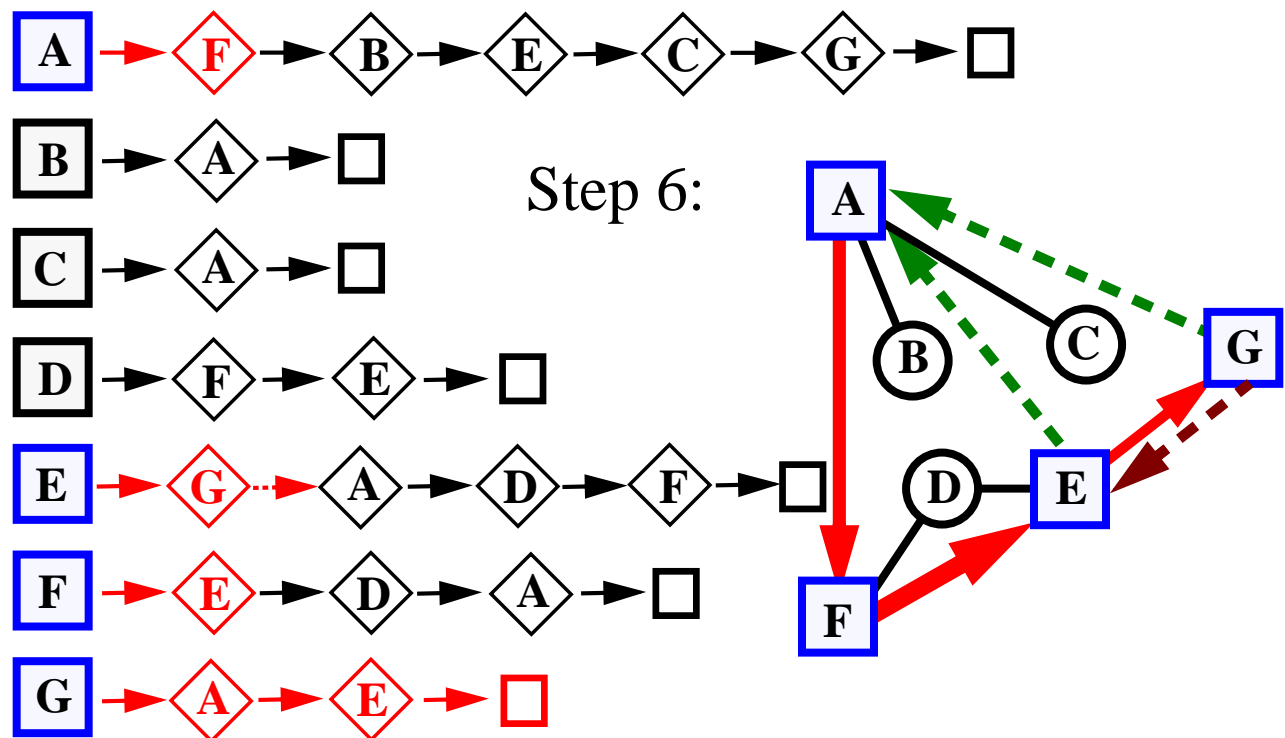
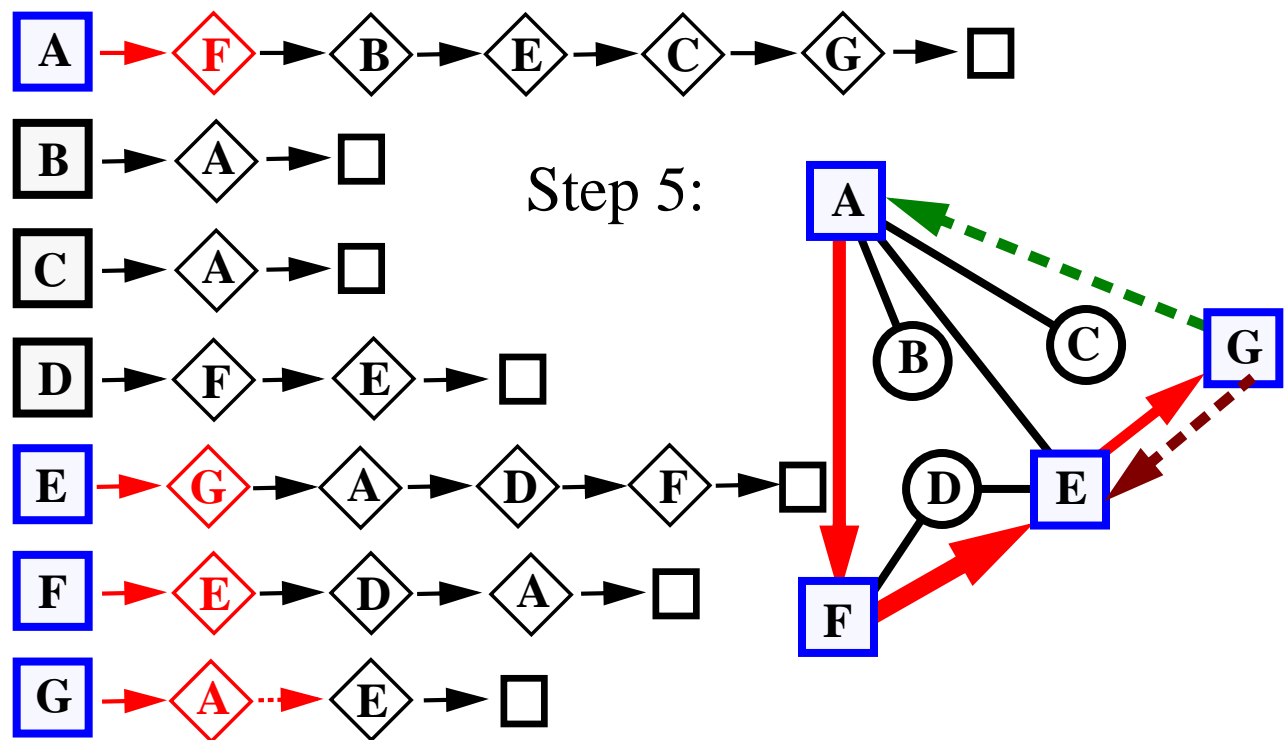
Step 1:

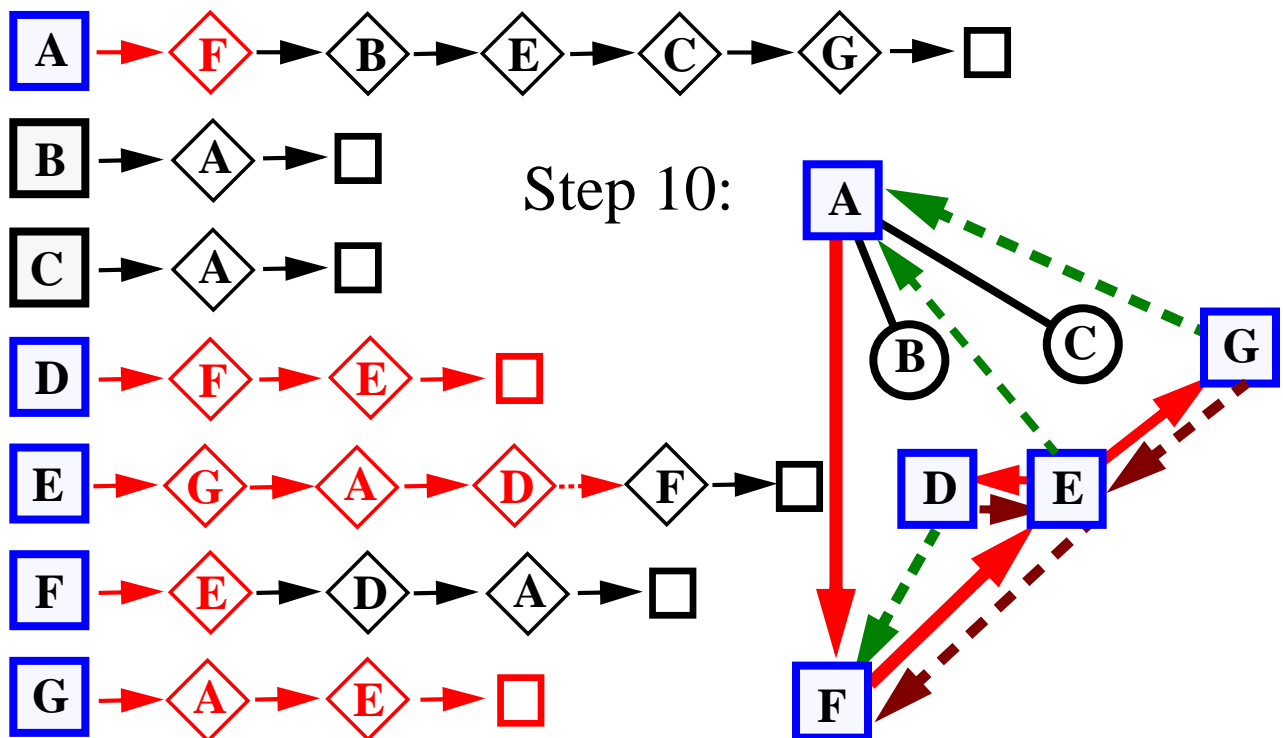
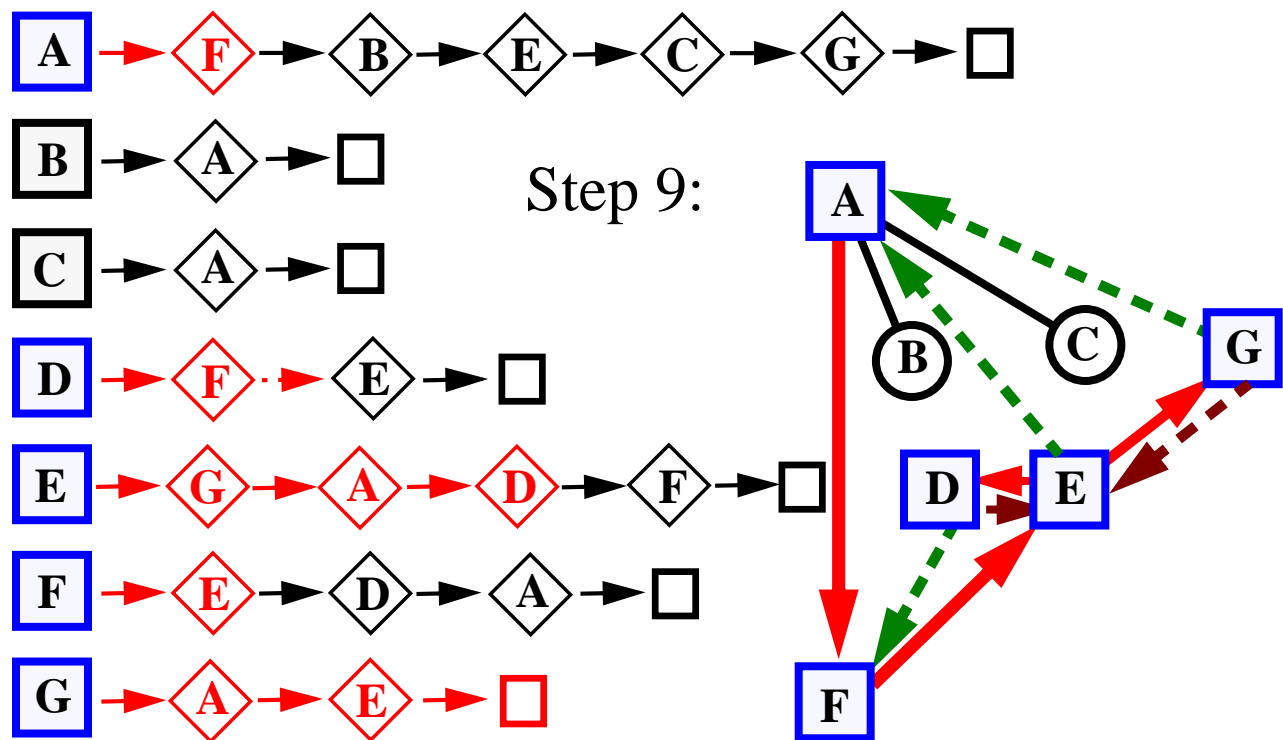


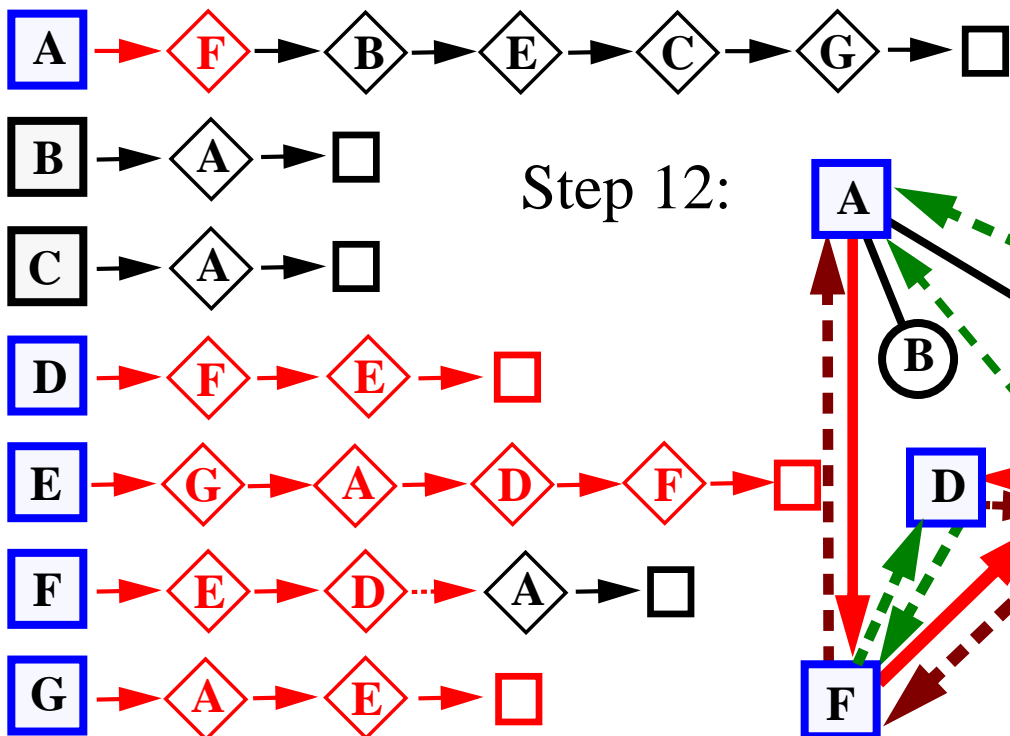
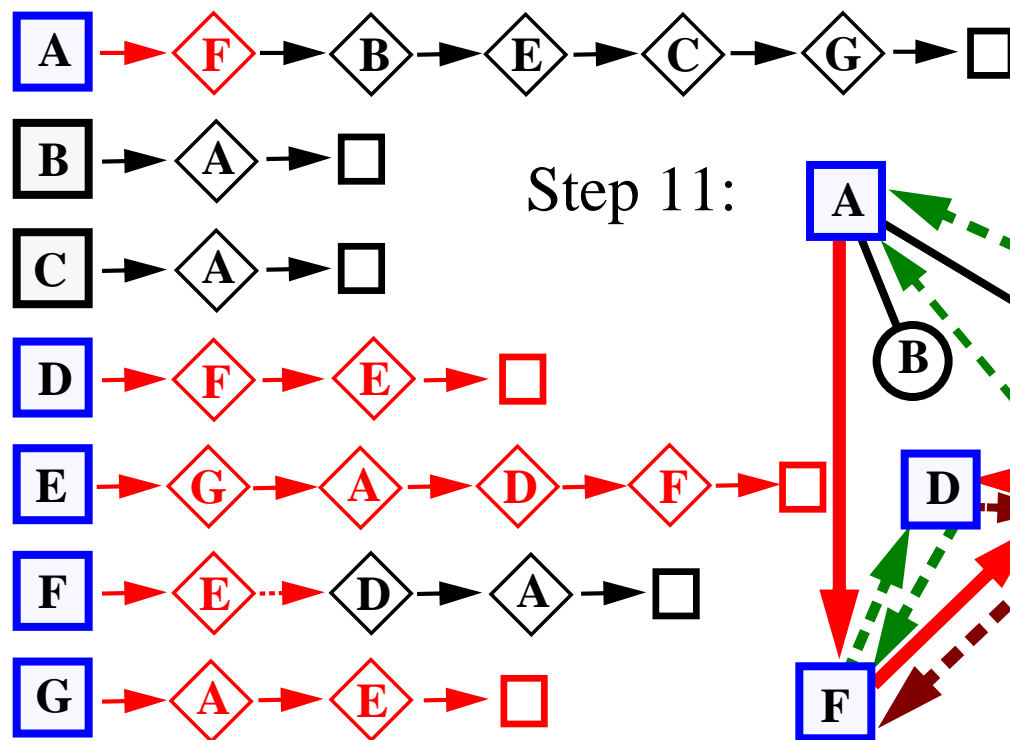
Step 2:

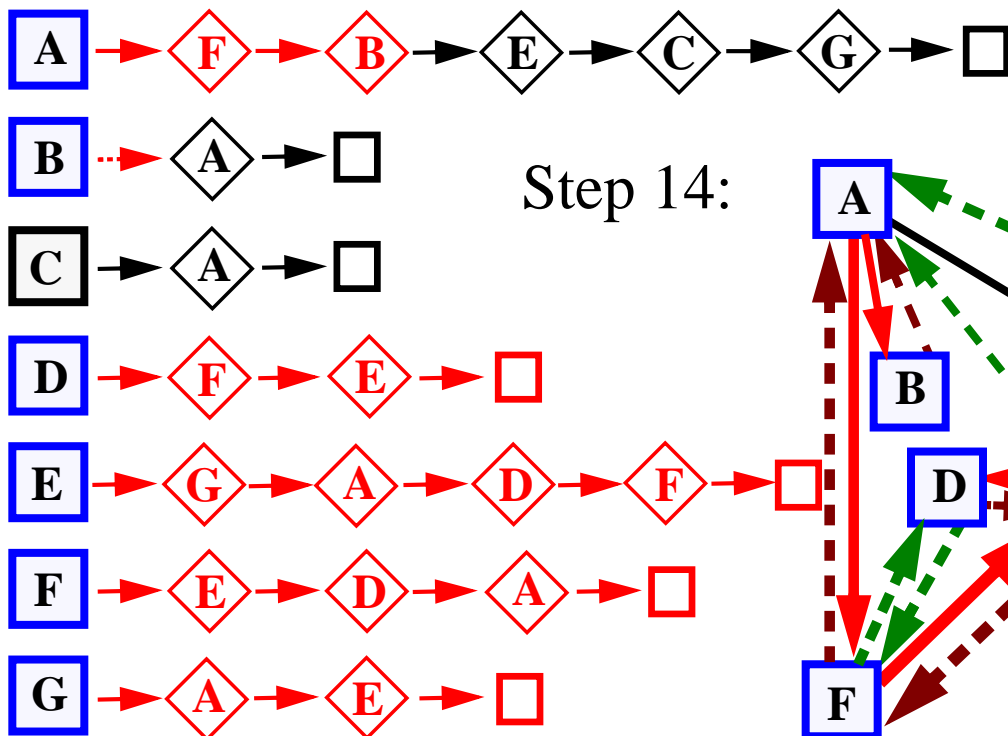
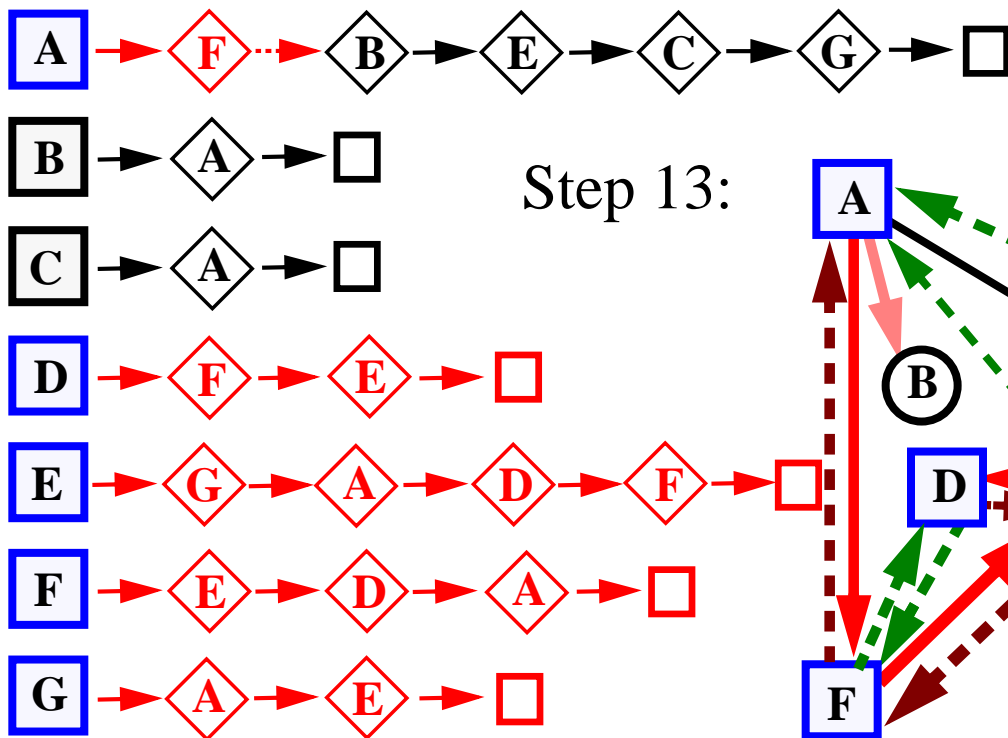


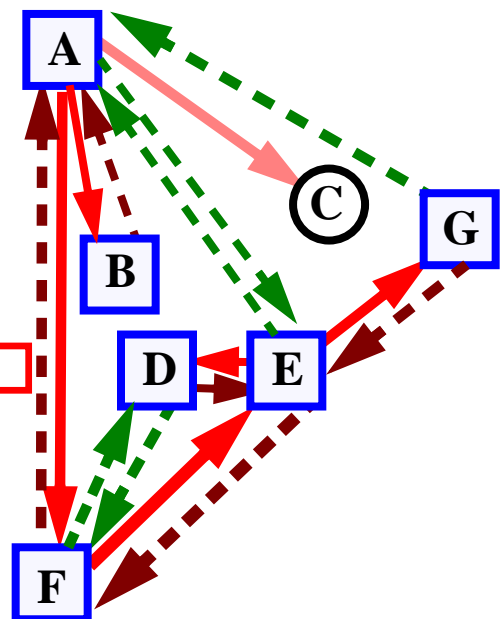
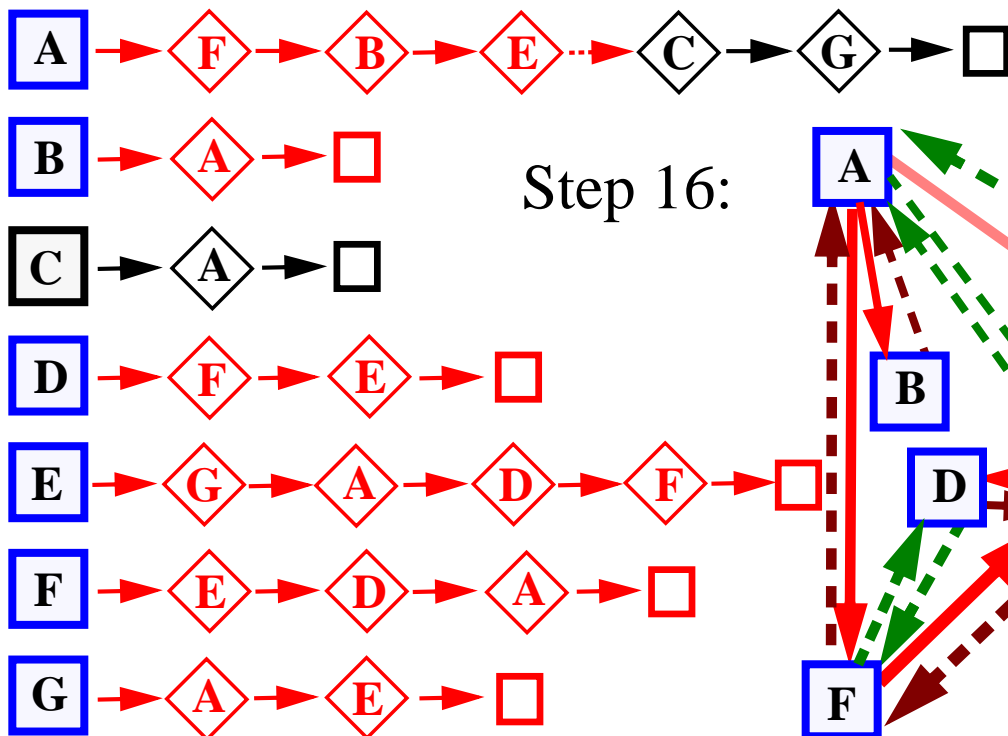
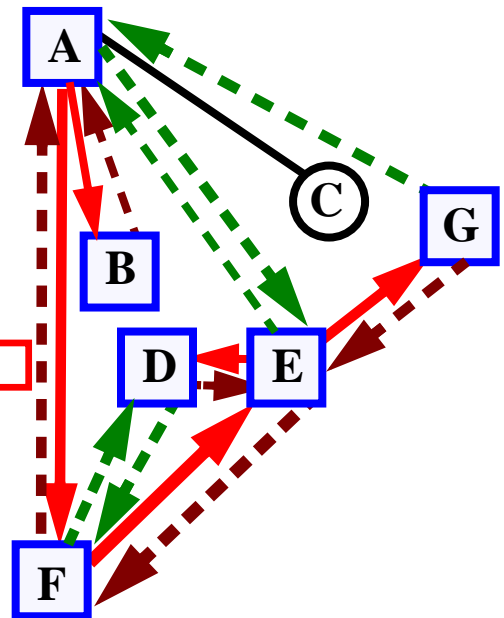
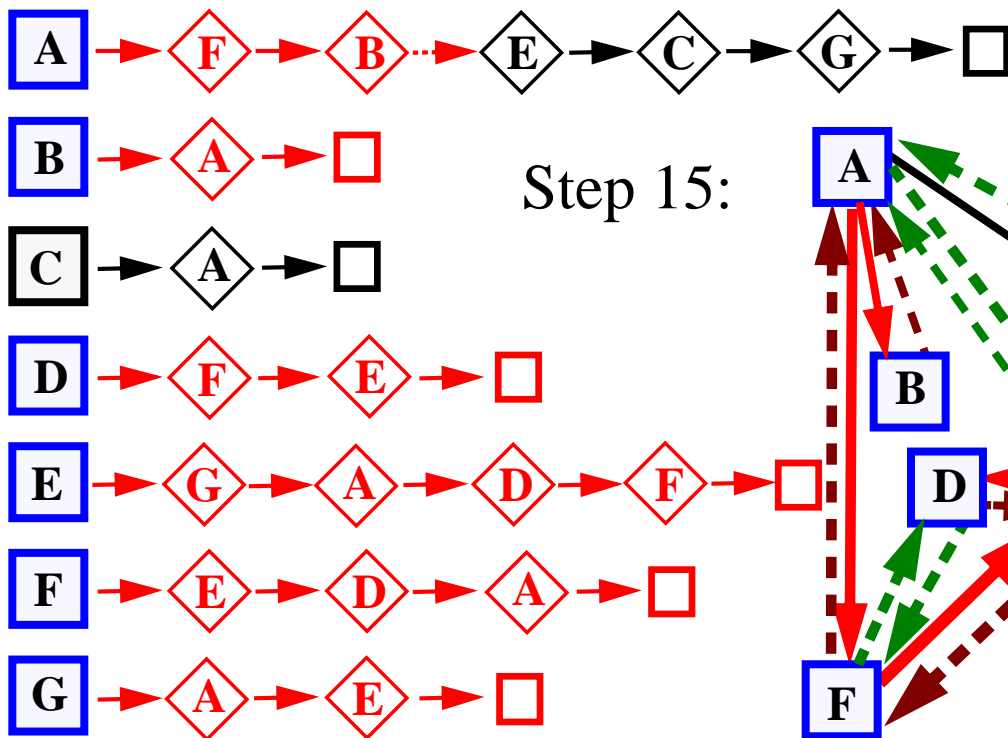


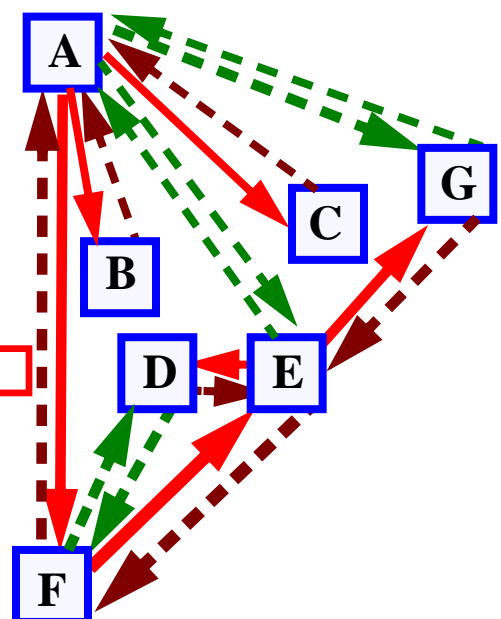
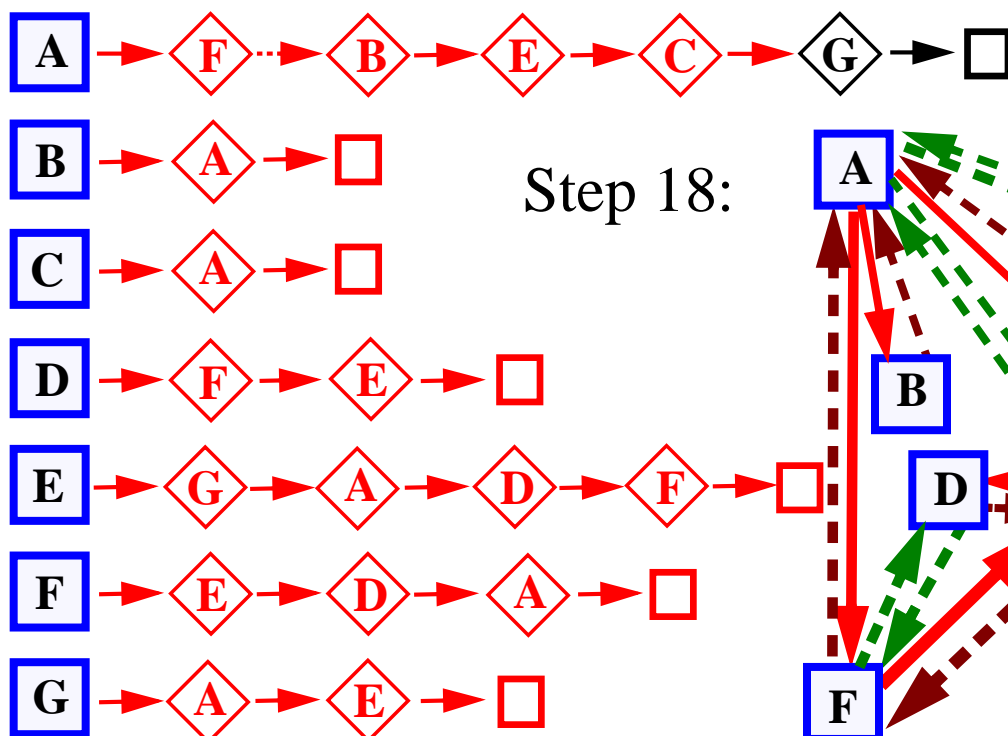
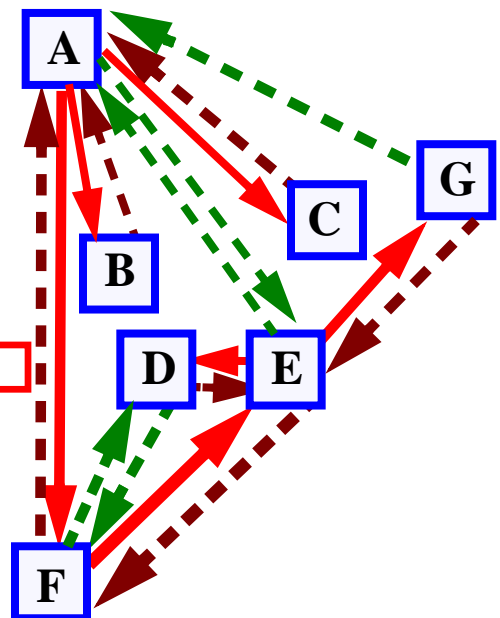
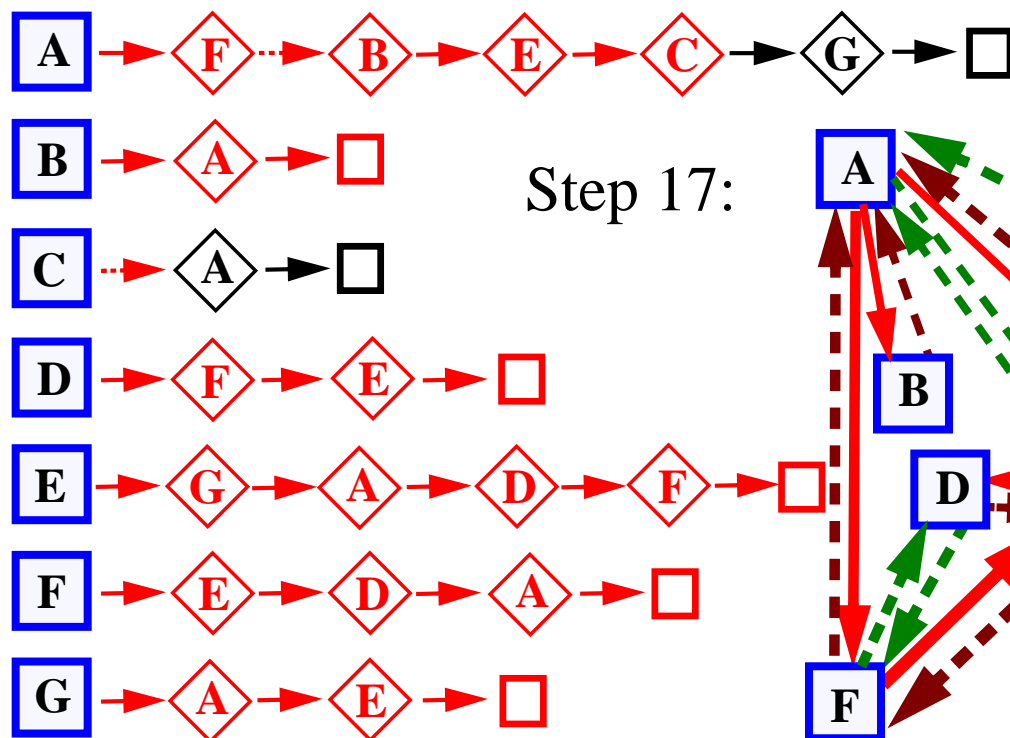


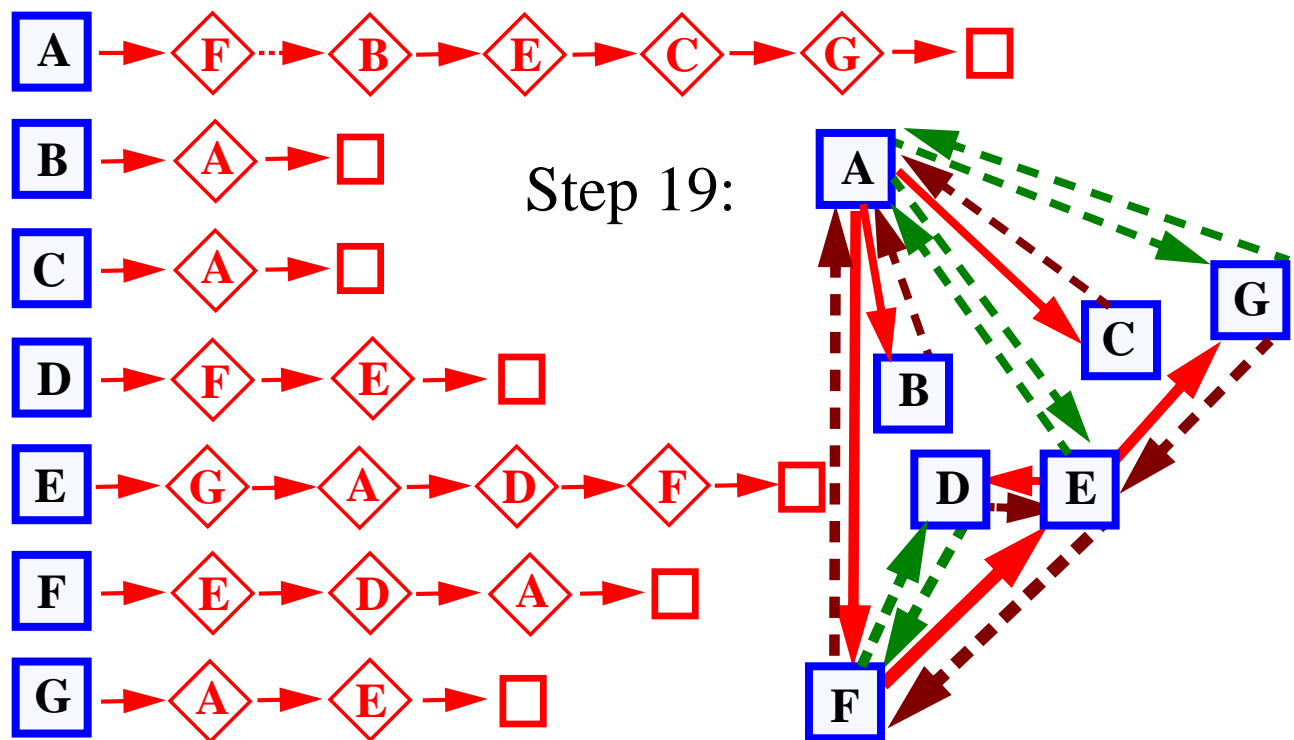












And we're done!

DFS Properties

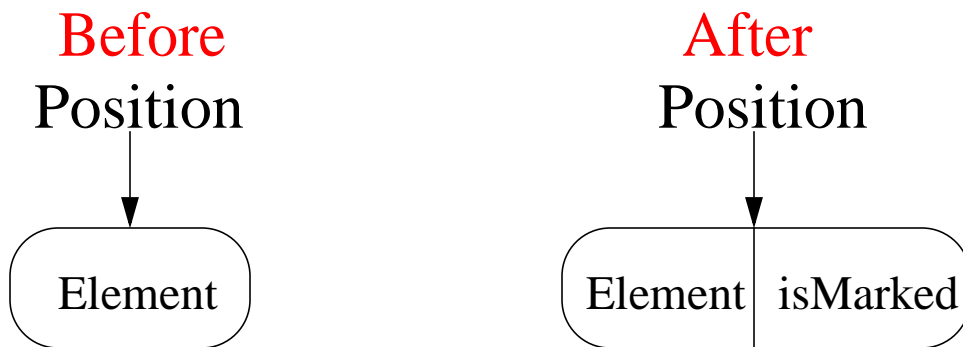
- Proposition 9.12 : Let G be an undirected graph on which a **DFS** traversal starting at a vertex s has been preformed. Then:
 - 1) The traversal visits all vertices in the connected component of s
 - 2) The discovery edges form a spanning tree of the connected component of s
- Justification of 1):
 - Let's use a contradiction argument: suppose there is at least one vertex v not visited and let w be the first unvisited vertex on some path from s to v .
 - Because w was the first unvisited vertex on the path, there is a neighbor u that has been visited.
 - But when we visited u we must have looked at edge (u, w) . Therefore w must have been visited.
 - and justification
- Justification of 2):
 - We only mark edges from when we go to unvisited vertices. So we never form a cycle of discovery edges, i.e. discovery edges form a tree.
 - This is a spanning tree because **DFS** visits each vertex in the connected component of s

Running Time Analysis

- Remember:
 - **DFS** is called on each vertex exactly once.
 - Every edge is examined exactly twice, once from each of its vertices
- For n_s vertices and m_s edges in the connected component of the vertex s , a **DFS** starting at s runs in $O(n_s + m_s)$ time if:
 - The graph is represented in a data structure, like the adjacency list, where vertex and edge methods take constant time
 - Marking a vertex as explored and testing to see if a vertex has been explored takes $O(\text{degree})$
 - By marking visited nodes, we can systematically consider the edges incident on the current vertex so we do not examine the same edge more than once.

Marking Vertices

- Let's look at ways to mark vertices in a way that satisfies the above condition.
- Extend vertex positions to store a variable for marking



- Use a hash table mechanism which satisfies the above condition is the probabilistic sense, because it supports the mark and test operations in $O(1)$ expected time